## **ATOMIC FORCES**

An object that is at rest will tend to remain at rest. An object that is in motion will tend to remain in motion unless acted upon by an outside force.

-Isaac Newton

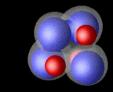
## THIS LECTURE

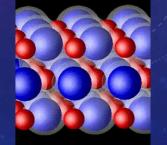
- Atomic motion and *ab initio* computation of forces
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## ATOMIC MOTIONS

- Born-Oppenheimer:  $e^{-r}$ 's adjust instantaneously to atomic locations  $\Rightarrow E_0(\vec{R}_1, \vec{R}_2, ..., \vec{R}_N)$
- Atoms sufficiently heavy to be treated classically (most cases)  $\lambda_{\text{th}} = \frac{h}{\sqrt{2\pi M k_B T}} \approx 0.19 \text{ Å (Si), } 0.29 \text{ Å (C)} \quad \textcircled{O} \qquad 1.01 \text{ Å (H)} \quad \textcircled{O} \qquad 2PE = \frac{1}{2} \hbar \sqrt{\frac{k}{m}} \approx 0.027 \text{ eV (Si), } 0.041 \text{ eV (C)} \quad \textcircled{O} \qquad 0.140 \text{ eV (H)} \quad \textcircled{O} \qquad (H) \quad (H) \quad \textcircled{O} \qquad (H) \quad \textcircled{O} \qquad (H) \quad \textcircled{O} \qquad (H) \quad \textcircled{O} \qquad (H) \quad (H) \quad \textcircled{O} \qquad (H) \quad ($

• Classical physics  $\Rightarrow \vec{F}_I = M_I \frac{d^2}{dt^2} \vec{R}_I$ 





HELLMANN-FEYNMAN THEOREM Definition of force:  $\vec{F}_I = -\frac{d}{d\vec{R}_I}E_0(\{\vec{R}_I\})$ • For us:  $E_0(\vec{R}_I) = \min_{\psi_{n\vec{k}}} E_0(\vec{R}_I, \psi_{n\vec{k}})$ • Trick: Define  $\psi_{n\vec{k}}^{(0)}(\vec{R}_I) = \arg\min_{\psi_{\vec{x}}} E_0(\vec{R}_I, \psi_{n\vec{k}})$  $\Rightarrow E_0(\vec{R}_I) \equiv E_0(\vec{R}_I, \psi_{n\vec{k}}^{(0)}(\vec{R}_I))$ • Then,  $\vec{\mathrm{F}}_{I} = -\frac{d}{d\vec{R}_{I}}E_{0}(\vec{R}_{I},\psi_{n\vec{k}}^{(0)}(\vec{R}_{I}))$  $= -\frac{\partial}{\partial \vec{R}_{I}} E_{0}(\vec{R}_{I}, \psi_{n\vec{k}}^{(0)}(\vec{R}_{I})) - \sum_{n\vec{k}} \sum_{l=1}^{n} E_{0}(\vec{R}_{I}, \psi_{n\vec{k}}^{(0)}(\vec{R}_{I})) - \frac{d}{d\vec{R}_{I}} \psi_{n\vec{k}}^{(0)}(\vec{R}_{I})$ • But  $\frac{\partial}{\partial \psi_{n\vec{k}}} E_0(\vec{R}_I, \psi_{n\vec{k}}^{(0)}(\vec{R}_I)) = 0$  (minimum!), so  $\vec{F}_I = -\frac{\partial}{\partial \vec{R}_I} E_0(\vec{R}_I, \psi_{n\vec{k}}^{(0)}(\vec{R}_I))$ • Fixed- $\psi_{n\vec{k}}$  derivative  $\frac{\partial E_0}{\partial \vec{R}_I} = \frac{\partial}{\partial \vec{R}_I} (T_e + V_{ee} + V_{NN} + V_{eN}) = \frac{\partial V_{NN}}{\partial \vec{R}_I} + \frac{\partial V_{eN}}{\partial \vec{R}_I}$  are "easy" only issue: need to know  $\psi_{n\vec{k}}^{(0)}$  from  $E_0$  calculation ! ( 🜚 )

## THIS LECTURE

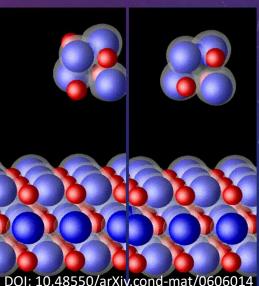
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AB INITIO MOLECULAR DYNAMICS (AIMD)  $\vec{F}_I = M_I \frac{d^2 \vec{R}_I}{dt^2}$ 

• Verlet algorithm (time reversible, conserves energy)  $\vec{F}_{I}\left(\vec{R}_{I}(t_{n})\right) = M_{I} \frac{\frac{\vec{R}_{I}(t_{n+1}) - \vec{R}_{I}(t_{n})}{\Delta t} - \frac{\vec{R}_{I}(t_{n}) - \vec{R}_{I}(t_{n-1})}{\Delta t}}{\Delta t} = M_{I} \frac{\vec{R}_{I}(t_{n+1}) - 2\vec{R}_{I}(t_{n}) + \vec{R}_{I}(t_{n-1})}{\Delta t^{2}}$   $\Rightarrow$ 

$$\mathcal{O}\vec{R}_{I}(t_{n+1}) = 2\vec{R}_{I}(t_{n}) - \vec{R}_{I}(t_{n-1}) + \frac{\Delta t^{2}}{M_{I}}\vec{F}_{I}(\vec{R}_{I}(t_{n}))$$

Study of impact of cluster temperatures on PLD of MgO
⇒ "Hot" incoming MgO PLD clusters have higher sticking coefficient that "cold" clusters (*Freedman and Arias*)



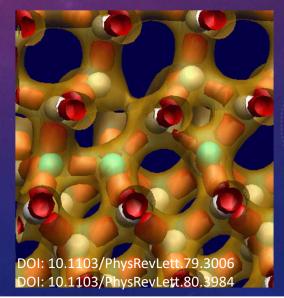
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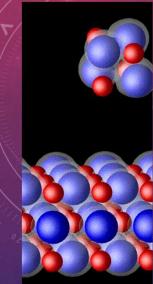
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## EQUILIBRIUM STRUCTURES

- Over time,  $\vec{R}_I$ 's settle into lowest energy configuration (simulated annealing)
- Short cut:  $\bigcup \vec{R}_I \leftarrow \vec{R}_I + \epsilon \vec{F}_I(\vec{R}_I)$ (gradient descent:  $\vec{F}_I = -\nabla_{\vec{R}_I} E_0$ )
- Led to discovery of paramagnetically active, 5-fold coordinated Si atom in core of 30° partial dislocation (*Engeness, Csanyi, Arias*)

Always verify your iterative convergence! ( ② )





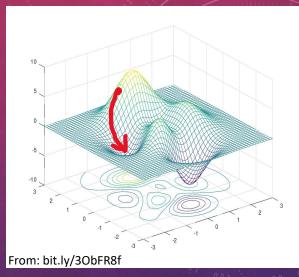
## MULTIPLE MINIMA PROBLEM

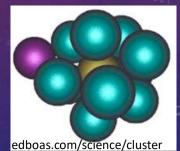
 Gradient descent finds "nearest" local minimum (e<sup>-</sup> minimization is convex\*, has only 1 minimum (20) !)
\*Except magnetic systems (multiple magnetic orderings)

- Global minimum problem is unsolved
  - Subject of ML approaches
  - Simulated annealing
  - Chemical intuition

All approaches descend from set of reasonable starting locations

Nature often exhibits multiple structure/phases

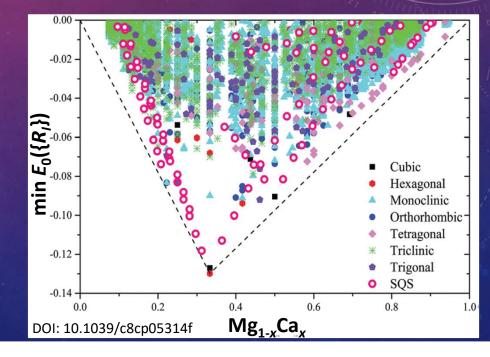




### DETERMINATION OF STABLE PHASES

#### **Thermodynamic construction**

- Compute min E<sub>0</sub>(R<sub>1</sub>) for "exhaustive" list of minima
- Construct convex hull diagram
- Stable, realizable phases occur at vertices



# THANK YOU!

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